

# [ZPL Linux SDK]

[Printer ZPL Command Development Manual v2.0.4]

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# 1. Information of the Manual

This SDK manual provides the so file information for Linux application development. We continuously promote and update the function and quality of all our products. Any change to the product specification and the manual will be without any further notice.

## 2. Operation System

Linux debian 5.10.0 and above.

## 3. Remark

1. When error code Return Value is greater than 0, it is the internal error of Linux system, please refer to related help file.
2. The printer resolution is 200 dpi,1 mm=8 dot;The printer resolution is 300 dpi,1 mm=12 dot.
3. The SDK references third-party libraries: libserialport, libusb-1.0. Please install it in the operating system in advance.
4. Serial port connection requires root privileges.

## 4. Method

### 4.1.InitPrinter

Set up the target printer of specified model (the printer object must be created before any printer operation).

```
void* InitPrinter (  
    const TCHAR* model  
);
```

**Parameter:**

*const TCHAR\* model*  
[in] Specify the model of target printer.

**Return Value:**

success:Returns a handle to the printer object  
fail:Return NULL

### 4.2.ReleasePrinter

The method is to release the resources of the printer object (the created printer object must be released after the operation is completed ).

```
int ReleasePrinter (  
    void* hPrinter
```

);

**Parameter:**

*void\* hPrinter*

[in] Handle to the target printer object that needs to be released

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory

## 4.3.OpenPort

Open the communication port and connect with the printer. After successfully connected, other functions can be used. If failed connecting, please check the error information. Currently it supports USB, internet, serial interface.

```
int OpenPort (  
    void* hPrinter,  
    const TCHAR* setting  
);
```

**Parameter:**

*void\* hPrinter*

[in] The created target printer object.

*const TCHAR\* setting*

[in] Set the communication port parameters to connect to the target printer. See the table below for details:

Configuration List:

Type	Configuration	Description	Sample
USB	USB,path	USB,USB path	USB,/001/007
NET	NET, IP address (IPV4)[,port]	Specify the IPAddress and port.If no port is specified,The default port is 9100.	NET,192.168.1.10 NET,192.168.1.10,9100
COM	COM,path,rate	Specify the connected serial port path and baud rate.	COM10,19200

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_USB_DEVICE_NOT_FOUND	-17	Failed, device not found
ERROR_IO_OPEN_FAILED	-8	Failed to open port

## 4.4.ClosePort

This function is to close the communication port and disconnect with the printer.

```
int ClosePort (  
    void* hPrinter  
);
```

**Parameter:**

*void\* hPrinter*  
[in] The created target printer object.

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-3	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-2	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory

## 4.5.WriteData

This function is to send data to the printer.

```
int WriteData(  
    void* handle,  
    unsigned char* buffer,  
    unsigned int size  
);
```

**Parameter:**

*void\* handle*  
[in] The created target printer object.  
*unsigned char\* buffer*  
[in] The data sent to the printer (hex string).  
*unsigned int size*  
[in] The length of the sent data.

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out

## 4.6.ReadData

This function is to read the printer data.

```
int ReadData(  
    void* handle,  
    unsigned char* buffer,
```

```

        unsigned int size
    );

```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*unsigned char\* buffer*

[in] Printer data to be read.

*unsigned int size*

[in] The length of the data to be read.

**Return Value:**

Code	Value	Description
>0	>0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_OPEN_FAILED	-8	Failed to open port

## 4.7. ZPL\_StartFormat

This function is to indicate the beginning of a new label format.

```

int ZPL_StartFormat(
    void* handle
);

```

**Parameter:**

*void\* handle*

[in] The created target printer object.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.8. ZPL\_EndFormat

This function is to indicate the end of a label format.

```

int ZPL_EndFormat(
    void* handle
);

```

**Parameter:**

*void\* handle*

[in] The created target printer object.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.9. ZPL\_ScalableFontText

This function is to print scalable fonts.

```
int ZPL_ScalableFontText(
    void* handle,
    int xPos,
    int yPos,
    char fontName,
    int orientation,
    int fontWidth,
    int fontHeight,
    const TCHAR* text
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*char fontName*

[in] Font(range: A-Z and 0-9).

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int fontWidth*

[in] Font width.

*int fontHeight*

[in] Font height.

*const TCHAR\* text*

[in]Text data.

### Return Value:

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system



## 4.10. ZPL\_Text

This function is to print text.

```
int ZPL_Text(
    void* handle,
    int xPos,
    int yPos,
    int fontNum,
    int orientation,
    int fontWidth,
    int fontHeight,
    const TCHAR* text
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int fontNum*

[in] Font.

0 : FONT 0 - Scalable font

1 : FONT A - Bitmap font

2 : FONT B - Bitmap font

3 : FONT D - Bitmap font

4 : FONT E - Bitmap font

5 : FONT F - Bitmap font

6 : FONT G - Bitmap font

7 : FONT H - Bitmap font

8 : FONT P - Bitmap font

9 : FONT Q - Bitmap font

10 : FONT R - Bitmap font

11 : FONT S - Bitmap font

12 : FONT T - Bitmap font

13 : FONT U - Bitmap font

14 : FONT V - Bitmap font

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int fontWidth*

[in] Font width.

*int fontHeight*

[in] Font height.

Note: When FONT A is selected, the minimum width and height are 5\*9, and can only be multiplied.

```
FONT A -- 12345
FONT B -- 12345 UPPER CASE ONLY
FONT D -- 12345
FONT E -- (OCR-B) ABCDwxyz 12345
FONT F -- ABCDwxyz 12345
FONT G -- AByz 12
FONT H -- (OCR-A) UPPER CASE ONLY
FONT 0 -- (Scaleable) ABCDwxyz 12345
FONT GS -- @ ® ™
FONT P -- ABCDwxyz 12345
FONT Q -- ABCDwxyz 12345
FONT R -- ABCDwxyz 12345
FONT S -- ABCDwxyz 12345
FONT T -- ABCDwxyz 12345
FONT U -- ABCDwxyz 12345
FONT V -- ABCDwxyz 12345
```

FONT	H x W (in dots)
A	9 x 5
B	11 x 7
D	18 x 10
E	28 x 15

F	26 x 13
G	60 x 40
H	21 x 13
GS	24 x 24
P	20 x 18
Q	28 x 24
R	35 x 31
S	40 x 35
T	48 x 42
U	59 x 53
V	80 x 71
O	15 x 12

*const TCHAR\* text*  
[in]Text data.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.11. ZPL\_BarCode39

This function is to print Barcode39 barcodes.

```
int ZPL_BarCode39(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int moduleWidth,
    int codeHeight,
    char line,
    char lineAboveCode,
    char digit,
    const TCHAR* text
);
```

**Parameter :**

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int moduleWidth*  
[in] Bar code width (range: 0- 10,unit:dot).

*int codeHeight*  
[in] Bar code height(range: 1-32000,unit:dot).

*char line*  
[in] Comment line.  
'N': not print  
'Y': print

*char lineAboveCode*  
[in] The comment line above the barcode.  
'N': not print above the barcode  
'Y': print above the barcode

*char digit*  
[in] Check Digit.  
'N': do not print check digit  
'Y': print check digit

*const TCHAR\* text*  
[in] Text data.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.12. ZPL\_Pdf417

This function is to print the Pdf417 code.

```
int ZPL_Pdf417(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int moduleWidth,
    int codeHeight,
    int securityLevel,
    int column,
    int rows,
    char truncate,
    const TCHAR* text
);
```

**Parameter:**

*void\* handle*  
[in]The created target printer object.

*int xPos*  
[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*  
[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*  
[in] Print direction.

0 : normal  
 90 : Rotate 90 degrees clockwise  
 180: Rotate 180 degrees clockwise  
 270: Rotate 270 degrees clockwise

*int moduleWidth*

[in] Bar code width (range: 0- 10,unit:dot).

*int codeHeight*

[in] Bar code height(range: 1-32000,unit:dot).

*int securityLevel*

[in] Security level (range:1-8).

*int column*

[in] The number of columns to encode.

*int rows*

[in] The number of rows to encode.

*char truncate*

[in] Truncated layer indication and stop mode.

'N': not truncated

'Y': execution truncation

*const TCHAR\* text*

[in] QR code data.

#### Return Value :

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

### 4.13. ZPL\_CodeEan8

This function is to print CodeEan8 barcodes.

```
int ZPL_CodeEan8(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int moduleWidth,
    int codeHeight,
    char line,
    char lineAboveCode,
    const TCHAR* text
);
```

#### Parameter:

*void\* handle*

[in]The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] Print direction.

0 : normal  
 90 : Rotate 90 degrees clockwise  
 180: Rotate 180 degrees clockwise  
 270: Rotate 270 degrees clockwise

*int moduleWidth*

[in] Bar code width (range: 0- 10,unit:dot).

*int codeHeight*

[in] Bar code height(range: 1-32000,unit:dot).

*char line*

[in] Comment line.

'N': not print

'Y': print

*char lineAboveCode*

[in] The comment line above the barcode.

'N': not print above the barcode

'Y': print above the barcode

*const TCHAR\* text*

[in] Text data.

#### Return Value :

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.14. ZPL\_UpceCode

This function is to print UPC- E barcodes.

```
int ZPL_UpceCode(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int moduleWidth,
    int codeHeight,
    char line,
    char lineAboveCode,
    const TCHAR* text
);
```

#### Parameter:

*void\* handle*

[in]The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int moduleWidth*

[in] Bar code width (range: 0- 10,unit:dot).

*int codeHeight*

[in] Bar code height(range: 1-32000,unit:dot).

*char line*

[in] Comment line.

'N': not print

'Y': print

*char lineAboveCode*

[in] The comment line above the barcode.

'N': not print above the barcode

'Y': print above the barcode

*const TCHAR\* text*

[in] Text data.

#### Return Value :

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.15. ZPL\_BarCode93

This function is to print Barcode93 barcodes.

```
int ZPL_BarCode93(  
    void* handle,  
    int xPos,  
    int yPos,  
    int orientation,  
    int moduleWidth,  
    int codeHeight,  
    char line,  
    char lineAboveCode,  
    char digit,  
    const TCHAR* text  
);
```

#### Parameter :

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int moduleWidth*  
[in] Bar code width (range: 0- 10,unit:dot).

*int codeHeight*  
[in] Bar code height(range: 1-32000,unit:dot).

*char line*  
[in] Comment line.  
'N': not print  
'Y': print

*char lineAboveCode*  
[in] The comment line above the barcode.  
'N': not print above the barcode  
'Y': print above the barcode

*char digit*  
[in] Check Digit.  
'N': do not print check digit  
'Y': print check digit

*const TCHAR\* text*  
[in] Text data.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.16. ZPL\_BarCode128

This function is to print Barcode128 barcodes.

```
int ZPL_BarCode128(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int moduleWidth,
    int codeHeight,
    char line,
    char lineAboveCode,
    char checkDigit,
    char mode,
    const TCHAR* text
);
```

**Parameter :**

*void\* handle*  
[in] The created target printer object.

*int xPos*  
[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*  
[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] Print direction.  
 0 : normal  
 90 : Rotate 90 degrees clockwise  
 180: Rotate 180 degrees clockwise  
 270: Rotate 270 degrees clockwise  
*int moduleWidth*  
 [in] Bar code width (range: 0- 10,unit:dot).  
*int codeHeight*  
 [in] Bar code height(range: 1-32000,unit:dot).  
*char line*  
 [in] Comment line.  
 'N': not print  
 'Y': print  
*char lineAboveCode*  
 [in] The comment line above the barcode.  
 'N': not print above the barcode  
 'Y': print above the barcode  
*char checkDigit*  
 [in] UCC check Digit.  
 'N': do not print check digit  
 'Y': print check digit  
*char mode*  
 [in] Mode.  
 'N': no choice mode  
 'U': UCC matching mode  
 'A': automatic mode  
 'D': UCC/ EAN mode  
*const TCHAR\* text*  
 [in] Text data.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.17. ZPL\_CodeEan13

This function is to print CodeEan13 barcodes.

```

int ZPL_CodeEan13(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int moduleWidth,
    int codeHeight,
    char line,
    char lineAboveCode,
    const TCHAR* text
);
  
```



**Parameter:***void\* handle*

[in]The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int moduleWidth*

[in] Bar code width (range: 0- 10,unit:dot).

*int codeHeight*

[in] Bar code height(range: 1-32000,unit:dot).

*char line*

[in] Comment line.

'N': not print

'Y': print

*char lineAboveCode*

[in] The comment line above the barcode.

'N': not print above the barcode

'Y': print above the barcode

*const TCHAR\* text*

[in] Text data.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

**4.18. ZPL\_MicroPdf417**

This function is to print MicroPdf417 codes.

```
int ZPL_MicroPdf417(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int moduleWidth,
    int codeHeight,
    int mode,
    const TCHAR* text
);
```

**Parameter:***void\* handle*

[in]The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int moduleWidth*

[in] Bar code width (range: 0- 10,unit:dot).

*int codeHeight*

[in] Bar code height(range: 1-32000,unit:dot).

*int mode*

[in] Mode(range: 0-33).

Mode (M)	Number of Data Columns	Number of Data Rows	% of Cws for EC	Max Alpha Characters	Max Digits
0	1	11	64	6	8
1	1	14	50	12	17
2	1	17	41	18	26
3	1	20	40	22	32
4	1	24	33	30	44
5	1	28	29	38	55
6	2	8	50	14	20
7	2	11	41	24	35
8	2	14	32	36	52
9	2	17	29	46	67
10	2	20	28	56	82
11	2	23	28	64	93
12	2	26	29	72	105
13	3	6	67	10	14
14	3	8	58	18	26
15	3	10	53	26	38
16	3	12	50	34	49
17	3	15	47	46	67
18	3	20	43	66	96
19	3	26	41	90	132
20	3	32	40	114	167
21	3	38	39	138	202
22	3	44	38	162	237
23	4	6	50	22	32
24	4	8	44	34	49
25	4	10	40	46	67
26	4	12	38	58	85
27	4	15	35	76	111
28	4	20	33	106	155
29	4	26	31	142	208
30	4	32	30	178	261
31	4	38	29	214	313
32	4	44	28	250	366
33	4	4	50	14	20

*const TCHAR\* text*

[in] Text data.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.19. ZPL\_QRCode

This function is to print a QR code.

```

int ZPL_QRCode(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int model,
    int dpi,
    char eccLevel,
    char input,
    char charMode,
    const TCHAR* text
);

```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int model*

[in] Set the QR code version (1 : original version, 2 : enhanced version).

*int dpi*

[in] Magnification factor (range: 1- 10).

*char eccLevel*

[in] Error correction level.

H : Ultra high reliability

Q: High reliability

M : standard level

L : high density level

*char input*

[in] Input mode。

A :Automatic Input

M : Manual Input

*char charMode*

[in] character Mode。

N: Numeric

A:Alphanumeric

B :8-bit byte mode

K : Kanji ,handles only Kanji characters in accordance with the Shift JIS system based on JIS X

0208. This means that all parameters after the character mode K should be 16- bit characters.

If there are any 8-bit characters (such as ASCII code), an error occurs.

*const TCHAR\* text*

[in] data.Only when charMode is B, the first four digits of the data should be the data size, for example, if the data is qrcode, pass 0006qrcode.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data

ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.20. ZPL\_UpcExtensions

This function is to print UPC extended barcodes.

```
int ZPL_UpcExtensions(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int moduleWidth,
    int codeHeight,
    char line,
    char lineAboveCode,
    const TCHAR* text
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int moduleWidth*

[in] Bar code width (range: 0- 10,unit:dot).

*int codeHeight*

[in] Bar code height(range: 1-32000,unit:dot).

*char line*

[in] Comment line.

'N': not print

'Y': print

*char lineAboveCode*

[in] The comment line above the barcode.

'N': not print above the barcode

'Y': print above the barcode

*const TCHAR\* text*

[in] Text data.

### Return Value:

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the

## 4.21. ZPL\_UpcaBarcode

This function is to print UPC-A barcodes.

```
int ZPL_UpcaBarcode(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int moduleWidth,
    int codeHeight,
    char line,
    char lineAboveCode,
    char digit,
    const TCHAR* text
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int moduleWidth*

[in] Bar code width (range: 0- 10,unit:dot).

*int codeHeight*

[in] Bar code height(range: 1-32000,unit:dot).

*char line*

[in] Comment line.

'N': not print

'Y': print

*char lineAboveCode*

[in] The comment line above the barcode.

'N': not print above the barcode

'Y': print above the barcode

*char digit*

[in] Check Digit.

'N': do not print check digit

'Y': print check digit

*const TCHAR\* text*

[in] Text data.

### Return Value:

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data

ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.22. ZPL\_SetChangeFontEncoding

This function is to select an international character set.

```
int ZPL_SetChangeFontEncoding(
    void* handle,
    int encodeType
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*int encodeType*

[in] Character set type (range: 0-31, 33-36).

0 : single byte encoding - US 1 character set

1 : Single-byte encoding - US 2 character set

2 : Single Byte Encoding - British Character Set

3 : Single Byte Encoding - Dutch Character Set

4 : Single-byte encoding - Danish/Norwegian character set

5 : Single-byte encoding - Swedish/Finnish character set

6 : Single byte encoding - German character set

7 : Single-byte encoding - French 1 character set

8 : Single-byte encoding - French 2 character set

9 : Single-byte encoding - Italian character set

10 : Single Byte Encoding - Spanish Character Set

11 : Single Byte Encoding - Miscellaneous Character Set

12 : Single-byte encoding - Japanese character set

13 : Code Page 850

14 : Double Byte Asian Code

15 : Shift-JIS

16 : EUC-JP and EUC-CN

17 : Not recommended - UCS-2 Big Endian

18-23 : Reserved

24 : Single Byte Asian Code

25 : Reserved

26 : Multibyte Asian Code

27 : Code Page 1252

28 : Unicode (UTF-8 encoding) - Unicode character set

29 : Unicode (UTF- 16 Big- Endian encoding) - Unicode character set

30 : Unicode (UTF- 16 Little- Endian encoding) - Unicode character set

31 : Code Page 1250

33 : Code page 1251

34 : Code page 1253

35 : Code page 1254

36 : Code page 1255

39 : Vietnam Character Set

### Return Value :

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory

ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.23. ZPL\_SetChangeCaret

This function is to change the format command prefix.

```
int ZPL_SetChangeCaret(
    void* handle,
    char character
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*char character*

[in] Format command prefix.

### Return Value:

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.24. ZPL\_SetChangeDelimiter

This function is to change the separator.

```
int ZPL_SetChangeDelimiter(
    void* handle,
    char character
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*char character*

[in] Separator.

### Return Value:

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out

Other values	Other values	the error code returned by the Linux system
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## 4.25. ZPL\_SetChangeTilde

This function is to change the control command prefix.

```
int ZPL_SetChangeTilde(
    void* handle,
    char character
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*char character*

[in] Control command prefix.

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.26. ZPL\_GraphicBox

This function is to draw a graphic box.

```
int ZPL_GraphicBox(
    void* handle,
    int xPos,
    int yPos,
    int width,
    int height,
    int thickness,
    int rounding
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int width*

[in] The width of the box (range: 1-32000, unit: dot).

*int height*

[in] The height of the box (range: 1-32000, unit: dot).



*int thickness*

[in] Boundary thickness (range: 1-32000, unit: dot).

*int rounding*

[in] Degree of rotation (range: 0-8).

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.27. ZPL\_GraphicCircle

This function is to draw a graphic circle.

```
int ZPL_GraphicCircle(  
    void* handle,  
    int xPos,  
    int yPos,  
    int diameter,  
    int thickness,  
);
```

**Parameter :**

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int diameter*

[in] Round diameter(range:3-4095,unit:dot).

*int thickness*

[in] Boundary thickness(range:1-4095,unit:dot).

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.28. ZPL\_GraphicDiagonalLine

This function is to draw diagonals.

```
int ZPL_GraphicDiagonalLine(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int width,
    int height,
    int thickness
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] The direction of the diagonal.

0x52(R or /) : right slanted diagonal

0x4c (L or \) : left slanted diagonal

*int width*

[in] The width of the box (range: 1-32000, unit: dot).

*int height*

[in] The height of the box (range: 1-32000, unit: dot).

*int thickness*

[in] Boundary thickness (range: 1-32000, unit: dot).

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.29. ZPL\_GraphicEllipse

This function is to draw a graphical ellipse.

```
int ZPL_GraphicEllipse(
    void* handle,
    int xPos,
    int yPos,
    int width,
    int height,
    int thickness
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).  
*int yPos*  
[in] Vertical starting position (range: 0-32000,unit:dot).  
*int width*  
[in] Ellipse width (range: 3-4095, unit: dot).  
*int height*  
[in] Ellipse height (range: 3-4095, unit: dot).  
*int thickness*  
[in] Boundary thickness (range: 2-4095, unit: dot).

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.30. ZPL\_PrintImage

This function is to print image(Only supports monochrome bmp format).

```
int ZPL_PrintImage(
    void* handle,
    int xPos,
    int yPos,
    const TCHAR* imgName
);
```

**parameter :**

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*const TCHAR\* imgName*

[in] The path to the image.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.31. ZPL\_GraphicSymbol

This function is to generate registered trademarks, copyright symbols and other symbols.

```
int ZPL_GraphicSymbol(  
    void* handle,  
    int xPos,  
    int yPos,  
    int orientation,  
    int width,  
    int height,  
    const char symbol  
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int width*

[in] Symbol width.

*int height*

[in] Symbol height.

*const char symbol*

[in] Data string.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.32. ZPL\_SetDiagnosticsMode

This function is to start the diagnostic mode.

```
int ZPL_SetDiagnosticsMode(  
    void* handle,  
    int isEnabled  
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int isEnabled*

[in] Whether to enable the diagnostic mode.

1 : Turn on diagnostic mode

0 : Cancel diagnostic mode

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

### 4.33. ZPL\_SetLabelHome

This function is to set the label home position.

```
int ZPL_SetLabelHome(  
    void* handle  
    int xPos,  
    int yPos  
);
```

**Parameter :**

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

### 4.34. ZPL\_SetLabelLength

This function is to set the label length.

```
int ZPL_SetLabelLength(  
    void* handle,  
    int length
```

);

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int length*

[in] Label length (range: 1-32000, unit: dot).

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.35. ZPL\_SetLabelShift

This function is to move the contents of the label to the left.

int ZPL\_SetLabelShift(  
    void\* handle,  
    int shift  
);

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int shift*

[in] The value to move to the left (range: -9999–9999, unit: dot).

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.36. ZPL\_SetLabelTop

This function is to move the position of the label up or down a short distance relative to the top edge of the label.

int ZPL\_SetLabelTop(  
    void\* handle,  
    int top  
);

**Parameter:***void\* handle*

[in] The created target printer object.

*int top*

[in] Maximum degree (range: - 120– 120, unit: dot).

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.37. ZPL\_SetPrintMode

This function is to set the action the printer performs after printing a label or label group.

```
int ZPL_SetPrintMode(
    void* handle,
    char mode,
    char prePeelSelect
);
```

**Parameter:***void\* handle*

[in] The created target printer object.

*char mode*

[in] Operating mode.

'T': tear open

'P': stripping (depending on the printer model)

'R': rewind (depending on the printer model)

'A': applicator (depending on printer model)

'C': cutter (depending on printer model)

'D': cutter delay

'F': RFID

'L': reserved

'U': reserved

'K': Kiosk

*char prePeelSelect*

[in] select.

'N': not execute

'Y': execute

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out

Other values	Other values	the error code returned by the Linux system
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## 4.38. ZPL\_SetMediaType

This function is to select the type of media used in the printer.

```
int ZPL_SetMediaType(
    void* handle,
    char type
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*char type*

[in] Media type.

'T' : thermal transfer media

'D' : direct thermal media

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.39. ZPL\_SetPrintingMirrorImage

This function is to print the entire printable area of the label as a mirror image.

```
int ZPL_SetPrintingMirrorImage(
    void* handle,
    char enable
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*char enable*

[in] Whether to open.

'N': not open

'Y': open

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory



ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.40. ZPL\_SetPrintOrientation

This function is to flip the label format 180 degrees.

```
int ZPL_SetPrintOrientation(
    void* handle,
    int orientation
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*int orientation*

[in] Whether to flip.

0 : don't flip

180: perform a flip

### Return Value:

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.41. ZPL\_SetPrintRate

This function is to set the print speed.

```
int ZPL_SetPrintRate(
    void* handle,
    int printSpeed,
    int slewSpeed,
    int backfeedSpeed
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*int printSpeed*

[in] Print speed. (unit: inches/sec)

*int slewSpeed*

[in] Swing speed. (unit: inches/sec)

*int backfeedSpeed*

[in] Feedback speed. (unit: inches/sec)

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

**4.42. ZPL\_SetPrintWidth**

This function is to set print width.

```
int ZPL_SetPrintWidth(
    void* handle,
    int width
);
```

**Parameter :**

*void\* handle*

[in] The created target printer object.

*int width*

[in] Set the print width (range: 2-944, unit: dot).

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

**4.43. ZPL\_SetSerialCommunications**

This function is to change the serial communication parameters.

```
int ZPL_SetSerialCommunications(
    void* handle,
    int baudRate,
    int wordLength,
    char parity,
    int stopBits,
    char protocolModo,
);
```

**Parameter :**

*void\* handle*

[in] The created target printer object.

*int baudRate*

[in] Bandwidth frequency. The scope is as follows:

110	300	600	1200	2400
4800	9600	14400	19200	28800
38400	57600	115200		

*int wordLength*

[in] Word length: 7-8, unit: data bits.

*char parity*

[in] as follows:

'N': means: none.

'E': means: even.

'O': means: odd.

*int stopBits*

[in] Range: 1-2.

*char protocolMode*

[in] as follows:

'X': indicates: XON/XOFF.

'D': indicates: DTR/ DSR.

'R': indicates: RTS.

'M': indicates: DTR/ DSR XON/XOFF r.

remark: 1 、XON/XOFF (transmitter on/transmitter off)

2 、DTR (Data Terminal Ready)

3 、DSR (Data Set Ready)

4 、RTS (Request To Send)

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.44. ZPL\_SetPrintDarkness

This function is to set print darkness.

```
int ZPL_SetPrintDarkness (
    void* handle,
    int darkness
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int darkness*

[in] Print darkness(Range: 0-30, unit: dot).

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory

ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.45. ZPL\_SetTearOffAdjustPosition

This function is to set the position where the label is torn away.

```
int ZPL_SetTearOffAdjustPosition (
    void* handle,
    int position
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*int position*

[in] Peel off position (range: - 120~+ 120).

### Return Value:

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.46. ZPL\_PrintConfigurationLabel

This function is to generate a printer configuration label.

```
int ZPL_PrintConfigurationLabel(
    void* handle
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

### Return Value:

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.47. ZPL\_GetPrinterIpAddress

This function is to get the printer IP address.

```
int ZPL_GetPrinterIpAddress(  
void* handle  
    char* ipAddress  
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*char\* ipAddress*

[in] Printer's IP address.

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.48. ZPL\_GetPrinterStatus

This function is to get the status of the printer.

```
int ZPL_GetPrinterStatus (  
    void* handle,  
    int* status  
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int \* status*

[in,out] The status of the printer.

Status	Value	Bit
Normal	0	-
The print head is opened	1	0
Paper jam	2	1
Out of paper	4	2
Out of ribbon	8	3
Print pause	16	4
Printing	32	5
Cover opened	64	6
Other error	128	7

**Return Value:**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.49. ZPL\_GetLabelLength

This function is to get the length of the label.

```
int ZPL_GetLabelLength (
    void* handle,
    char* length
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*char\* length*

[in] The length of the label.

### Return Value :

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.50. ZPL\_GetLabelWidth

This function is to get the width of the label.

```
int ZPL_GetLabelWidth(
    void* handle,
    char* width
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*char\* width*

[in] The width of the label.

### Return Value :

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.51. ZPL\_GetPrinterSeriesNumber

This function is to get the printer serial number.

```
int ZPL_GetPrinterSeriesNumber(
    void* handle,
    char* sn
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*char\* sn*

[in] Printer serial number.

### Return Value :

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.52. ZPL\_GetPrinterMacAddress

This function is to get the printer's MAC address.

```
int ZPL_GetPrinterMacAddress(
    void* handle,
    char* macAddressss
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*char\* macAddress*

[in] The MAC address of the printer.

### Return Value :

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

### 4.53. ZPL\_GetPrinterName

This function is to get the printer's name.

```
int ZPL_GetPrinterName(
    void* handle,
    char* name
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*char\* name*

[in] The name of the printer.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

### 4.54. ZPL\_GetPrinterFirmwareVersion

This function is to get the firmware version number of the printer.

```
int ZPL_GetPrinterFirmwareVersion(
    void* handle,
    char* version
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*char\* version*

[in] The firmware version number of the printer.

**Return Value :**



Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.55. ZPL\_GetPrinterDpi

This function is to get the resolution of the printer.

```
int ZPL_GetPrinterDpi(
    void* handle,
    char* dpi
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*char\* dpi*

[in] The resolution of the printer.

### Return Value :

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.56. ZPL\_GetPrinterModel

This function is to get the model of the printer.

```
int ZPL_GetPrinterModel(
    void* handle,
    char* model
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*char\* dpi*

[in] The model of the printer.

Eg:

```
char model[100] = { 0 };
ZPL_GetPrinterModel(printer, model);
printf("printer model is:%s\n", model);
```

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.57. ZPL\_LearnLabel

This feature is used for automatic label learning.

```
int ZPL_LearnLabel(
    void* handle,
);
```

**Parameter :**

*void\* handle*

[in] The created target printer object.

(The interface needs to be called before ZPL\_StartFormat)

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.58. ZPL\_SetReprintAfterError

This function is to reprint the labels that failed to print due to an error (error conditions include Ribbon Out, Media Out, Head Open).

```
int ZPL_SetReprintAfterError(
    void* handle,
    char* pEnable
);
```

**Parameter :**

*void\* handle*

[in] The created target printer object.

*char\* pEnable*

[in] Whether to enable reprint.

“on” : turn on reprint switch

“off” : close reprint switch

(The interface needs to be called before ZPL\_StartFormat)

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.59. ZPL\_SetMediaTracking

This function is to specify the media type being used and the black mark offset.

```
int ZPL_SetMediaTracking(  
    void* handle,  
    char mediaType,  
    int offset  
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*char mediaType*

[in] Media Type.

‘N’: continuous media(continuous paper)

‘Y’: non-continuous media web sensing(label paper)

‘W’: non-continuous media web sensing(label paper)

‘M’: non-continuous media mark sensing(black mark paper)

‘A’: auto-detects the type of media during calibration

‘V’: continuous media, variable length(Same as continuum, but if the portion of the printed label exceeds the defined label length, the label size will automatically expand to include them)

*int offset*

[in] Black mark offset (unused, set to 0) .

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.60. ZPL\_SetUserFontName

This function is to Set user-defined fonts,use for print text

```
int ZPL_SetPrintDefaultGateway (  
    void* handle  
    const TCHAR* text,  
    char alias  
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*const TCHAR\* text*

[in] Font name

*char alias*

[in] *alias*

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.61. ZPL\_Text\_Block

This function is to print text block.

```
int ZPL_Text_Block(  
    void* handle,  
    int xPos,  
    int yPos,  
    int fontNum,  
    int orientation,  
    int fontWidth,  
    int fontHeight,  
    int textBlockWidth,  
    int textBlockHeight,  
    const TCHAR* text  
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000,unit:dot).

*int yPos*

[in] Vertical starting position (range: 0-32000,unit:dot).

*int fontNum*

[in] Font.

- 0 : FONT O - Scalable font
- 1 : FONT A - Bitmap font
- 2 : FONT B - Bitmap font
- 3 : FONT D - Bitmap font
- 4 : FONT E - Bitmap font
- 5 : FONT F - Bitmap font
- 6 : FONT G - Bitmap font
- 7 : FONT H - Bitmap font
- 8 : FONT P - Bitmap font
- 9 : FONT Q - Bitmap font
- 10 : FONT R - Bitmap font
- 11 : FONT S - Bitmap font
- 12 : FONT T - Bitmap font
- 13 : FONT U - Bitmap font
- 14 : FONT V - Bitmap font

*int orientation*

[in] Print direction.

0 : normal

90 : Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int fontWidth*

[in] Font width.

*int fontHeight*

[in] Font height.

FONT	H x W (in dots)
A	9 x 5
B	11 x 7
D	18 x 10
E	28 x 15
F	26 x 13
G	60 x 40
H	21 x 13
GS	24 x 24
P	20 x 18
Q	28 x 24
R	35 x 31
S	40 x 35
T	48 x 42
U	59 x 53
V	80 x 71
O	15 x 12

*int textBlockWidth*

[in] Text block width

*int textBlockHeight*

[in] Text block height

*const TCHAR\* text*

[in]Text data.

Note: The data does not support Chinese at this time

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out

FONT A -- ABCDxyz 12345

FONT B -- ABCDxyz 12345 UPPER CASE ONLY

FONT D -- ABCDxyz 12345

FONT E -- (OCR-B)ABCDxyz 12345

FONT F -- ABCDxyz 12345

FONT G -- ABYz 12

FONT H -- (OCR-A) UPPER CASE ONLY

FONT O -- (Scaleable) ABCDxyz 12345

FONT GS -- ® ¢ ™ ®

FONT P -- ABCDxyz 12345

FONT Q -- ABCDxyz 12345

FONT R -- ABCDxyz 12345

FONT S -- ABCDxyz 12345

FONT T -- ABCDxyz 12345

FONT U -- ABCDxyz 12345

FONT V -- ABCDxyz 12345

Other values	Other values	the error code returned by the Linux system
--------------	--------------	---

## 4.62. ZPL\_SetPrintQuantity

This function is to gives control over several printing operations. It controls the number of labels to print, the number of labels printed before printer pauses, and the number of replications of each serial number.

```
int ZPL_SetPrintQuantity(
    void* handle,
    int totalQuantity,
    int pauseAndCutValue,
    int replicatesOfEachSerialNumber,
    char overridePauseCount
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*int totalQuantity*

[in] total quantity of labels to print (range: greater or equal to 1).

*int pauseAndCutValue*

[in] pause and cut value (range: greater or equal to 0,0 Means no pause).

*int replicatesOfEachSerialNumber*

[in] replicates of each.(range: greater or equal to 0).

*char overridePauseCount*

[in] Cut paper or pause.

'N': pause

'Y': Cut paper

### Return Value:

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.63. ZPL\_DataMatrixBarcode

This function is to print Data Matrix.

```
int ZPL_DataMatrixBarcode(
    void* handle,
    int xPos,
    int yPos,
    int orientation,
    int codeHeight,
```

```

    int level,
    int columns,
    int rows,
    int formatId,
    Int aspectRatio,
    const TCHAR* text
);

```

#### Parameter:

*void\* handle*

[in] The created target printer object.

*int xPos*

[in] Horizontal starting position (range: 0-32000, unit: dot).

*int yPos*

[in] Vertical starting position (range: 0-32000, unit: dot).

*int orientation*

[in] Printing direction.

0 : normal

90: Rotate 90 degrees clockwise

180: Rotate 180 degrees clockwise

270: Rotate 270 degrees clockwise

*int codeHeight*

[in] code height (range: 1-32000, unit: dot).

*int level*

[in] Security Level ( 0、50、80、100、140、200) 。

*int column*

[in] The number of columns to be encoded.

*int rows*

[in] The number of lines to be encoded.

*int formatId*

[in] Format id (0-6).

1 = Field data is number + space (0..9, ") - no \&' '

2 = Field data is uppercase alphanumeric + space (A..Z, ") – no \&' "

3 = Field data is uppercase alphanumeric + space, period, comma, dotted line and slash(0..9, A..Z, ".-/")

4 = The field data is uppercase alphanumeric + space (0..9, A..Z, ") – no \&' '

5 = The field data is a complete 128 ASCII 7-bit character set

6 = The field data is a complete 256 ASCII 8-bit character set

*int aspectRatio*

[in] Aspect ratio.

1 = square

2 = rectangle

*const TCHAR\* text*

[in] code data.

#### Return Value:

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.64. ZPL\_GetPrinterOdometer

This function is to get the number of printed mileage.

```
int ZPL_GetPrinterOdometer(  
    void* handle,  
    char* meters  
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*char\* meters*

[in] printed mileage.

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.65. ZPL\_SetPrintNetSetting

This function is to set the network port information.

```
int ZPL_SetPrintNetSetting(  
    void* handle,  
    const char* ipaddress,  
    const char* mask,  
    const char* gateway  
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*const char\* ipaddress*

[in] ip address. The format is : xxx.xxx.xxx.xxx

*const char\* mask*

[in] subnet mask .The format is : xxx.xxx.xxx.xxx

*const char\* gateway*

[in] default gateway The format is : xxx.xxx.xxx.xxx

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data



ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.66. ZPL\_WifiConfig

This function is to set wifi sta information.

```
int ZPL_WifiConfig(
    void* handle,
    int dhcp,
    const char* ipAddress,
    const char* mask,
    const char* gateway,
    const char* ssid,
    const char* password
);
```

### Parameter:

*void\* handle*

[in] The created target printer object.

*int dhcp*

[in] dhcp, Whether to open (0 : close, 1 : open)

*const char\* ipAddress*

[in] ip address. The format is : xxx.xxx.xxx.xxx

*const char\* mask*

[in] subnet mask .The format is : xxx.xxx.xxx.xxx

*const char\* gateway*

[in] default gateway The format is : xxx.xxx.xxx.xxx

*const char\* ssid*

[in] WiFi ssid.

*const char\* password*

[in] WiFi password.

### Return Value :

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.67. ZPL\_SetPrinterBluetoothSSID

This function is to set the Bluetooth SSID.

```
int ZPL_SetPrinterBluetoothSSID(
    void* handle,
```

```

        const TCHAR* ssid
    );

```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*const TCHAR\* ssid*

[in] ssid data (range: 1-32)

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.68. ZPL\_SetPrinterBluetoothPIN

This function is to set the Bluetooth pin code.

```

int ZPL_SetPrinterBluetoothPIN(
    void* handle,
    const TCHAR* pin
);

```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*const TCHAR\* pin*

[in] pin data (range: 1-32)

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.69. ZPL\_SetPrinterSleepTime

This function is to set the sleep time.

```

int ZPL_SetPrinterSleepTime(
    void* handle,
    int time,

```

);

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int time*

[in] sleep time(range: 0-10, unit: minute)

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.70. ZPL\_SetPrinterShutdownTime

This function is to set the automatic shutdown time.

```
int ZPL_SetPrinterShutdownTime(  
    void* handle,  
    int time,  
);
```

**Parameter:**

*void\* handle*

[in] The created target printer object.

*int time*

[in] Automatic shutdown time (range: 0-63, unit: minute)

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.71. ZPL\_FirmwareUpgrade

This function is to upgrade the printer firmware.

```
int ZPL_FirmwareUpgrade(  
    void* handle,  
    const TCHAR* cFileName,  
    void (*progressCallback)(float)
```

);

**Parameter:**

*void\* handle*

[in] The created target printer object.

*const TCHAR\* cFileName*

[in] Firmware file path

*void (\*progressCallback)(float)*

update progress callback

describe	Value
update progress	0~1
Update success	ERROR_CM_SUCCESS
Not enough memory	ERROR_CM_INSUFFICIENT_MEMORY
Failed to read file	ERROR_IO_READ_FAILED
Failed to send data	ERROR_IO_WRITE_FAILED

**Return Value :**

Code	Value	Description
ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system

## 4.72. ZPL\_FontDownload

This function is a font download.

int ZPL\_FontDownload(

*void\* handle,*

*const TCHAR\* cFileName,*

*void (\*progressCallback)(float)*

);

**Parameter:**

*void\* handle*

[in] The created target printer object.

*const TCHAR\* cFileName*

[in] Font file path

*void (\*progressCallback)(float)*

update progress callback

describe	Value
update progress	0~1
Update success	0
Not enough memory	-4
Failed to read file	-11
Failed to send data	-9

**Return Value :**

Code	Value	Description
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ERROR_CM_SUCCESS	0	success
ERROR_CM_INVALID_HANDLE	-2	failed with invalid handle
ERROR_CM_INVALID_PARAMETER	-1	Invalid argument
ERROR_CM_INSUFFICIENT_MEMORY	-4	failed, out of memory
ERROR_IO_WRITE_FAILED	-9	Failed to send data
ERROR_IO_READ_FAILED	-11	Failed to read data
ERROR_IO_WRITE_TIMEOUT	-10	Write data timed out
Other values	Other values	the error code returned by the Linux system